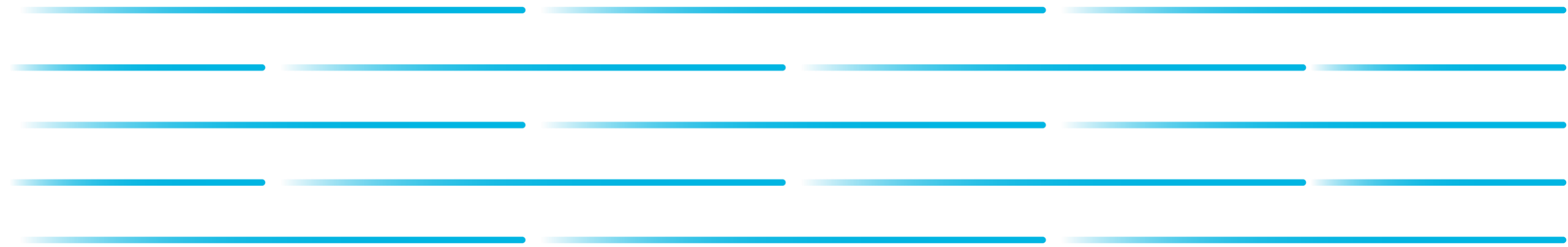




New Smart Multi-Ended Differential Protection for Power Networks

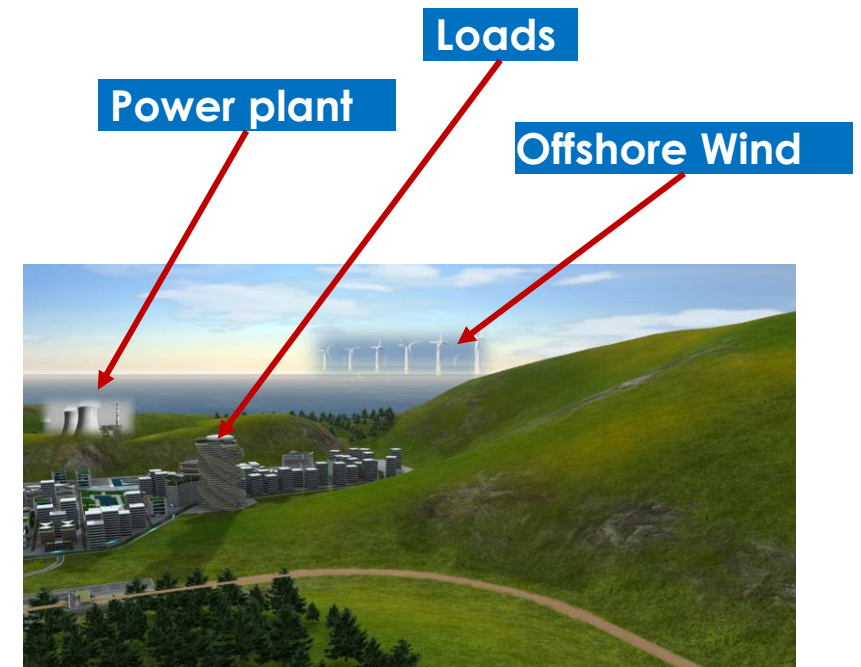
23 May 2017



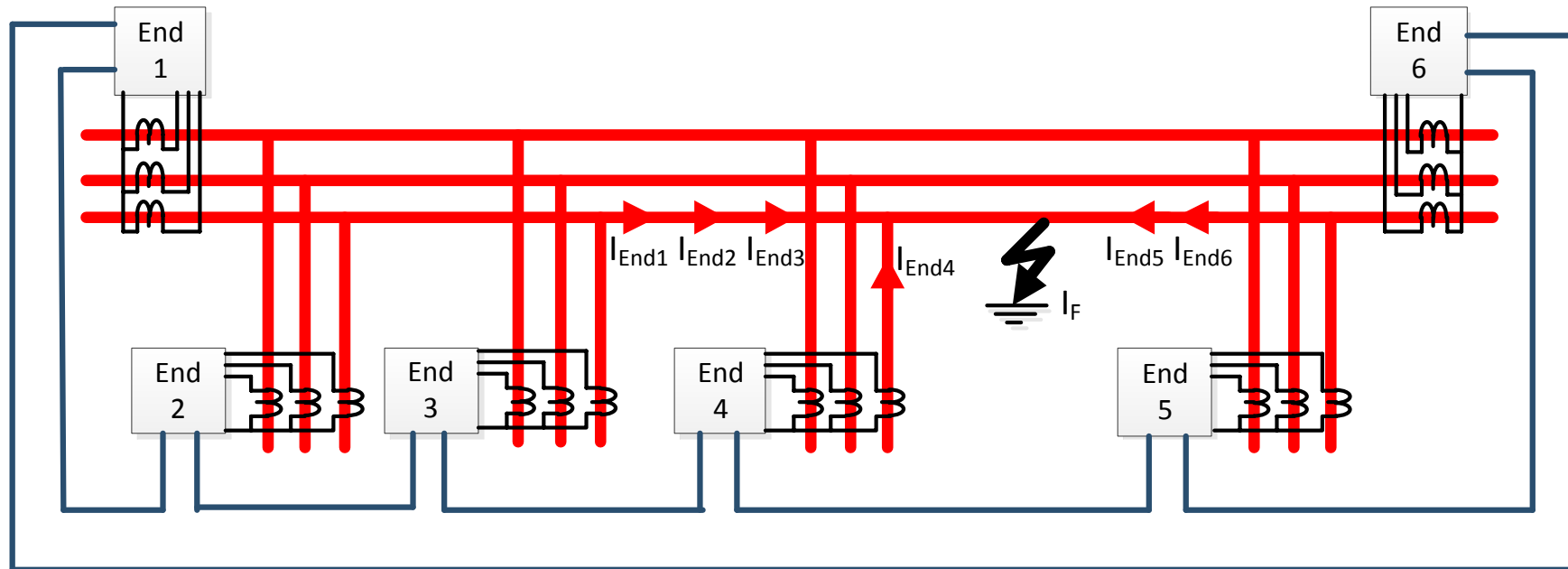
Introduction

Why multi-ended protection ?

- Utility power networks are evolving to transport power in ever more complex ring and meshed networks.
- For circuits which neighbour the coast, or other potential windfarm locations, those will be candidates for teed feeds to evacuate renewable energy.
- Line/cable differential protection becomes increasingly attractive, with its inherent ability to address grading/selectivity challenges and scalability for multi-terminal circuits to accommodate many connections of distributed



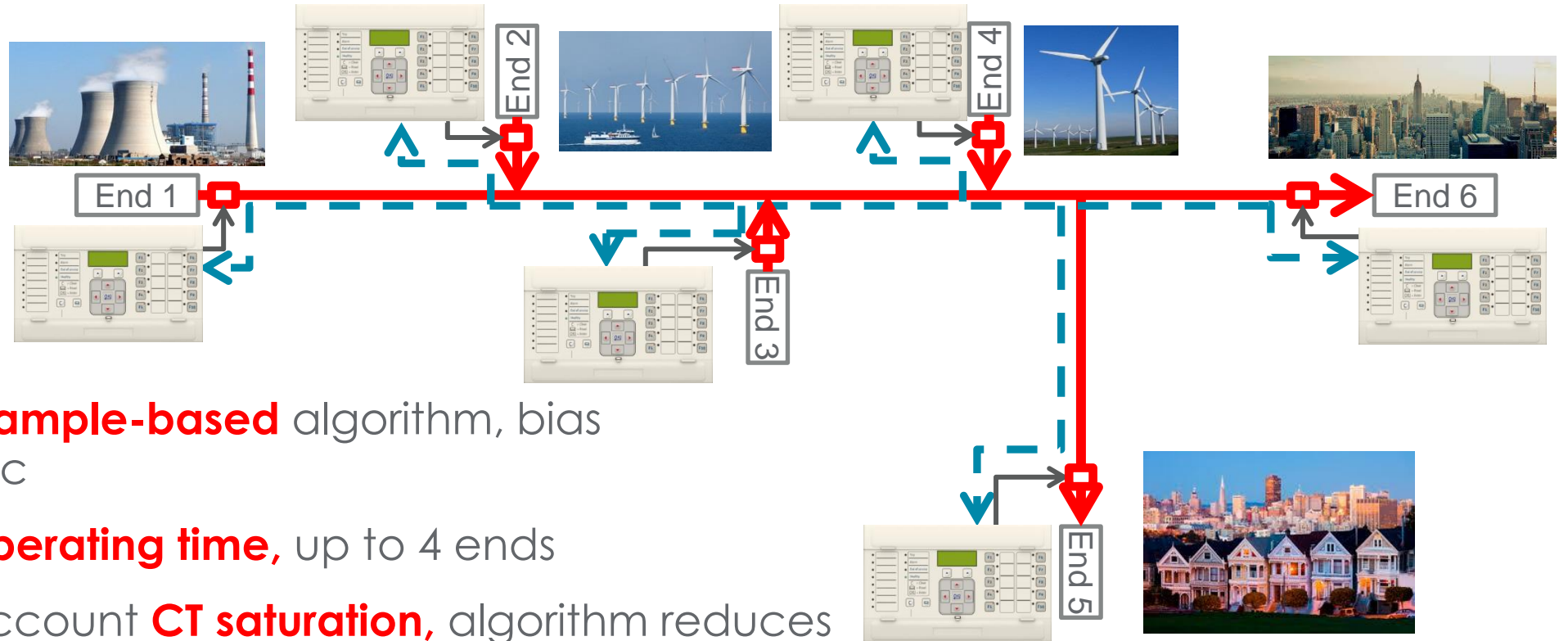
Line Differential Protection Principle



| | |
|--|---------|
| $I_{End1} + I_{End2} + I_{End3} + I_{End4} + I_{End5} + I_{End6} = 0$ | Healthy |
| $I_{End1} + I_{End2} + I_{End3} + I_{End4} + I_{End5} + I_{End6} \neq 0$ | Fault |



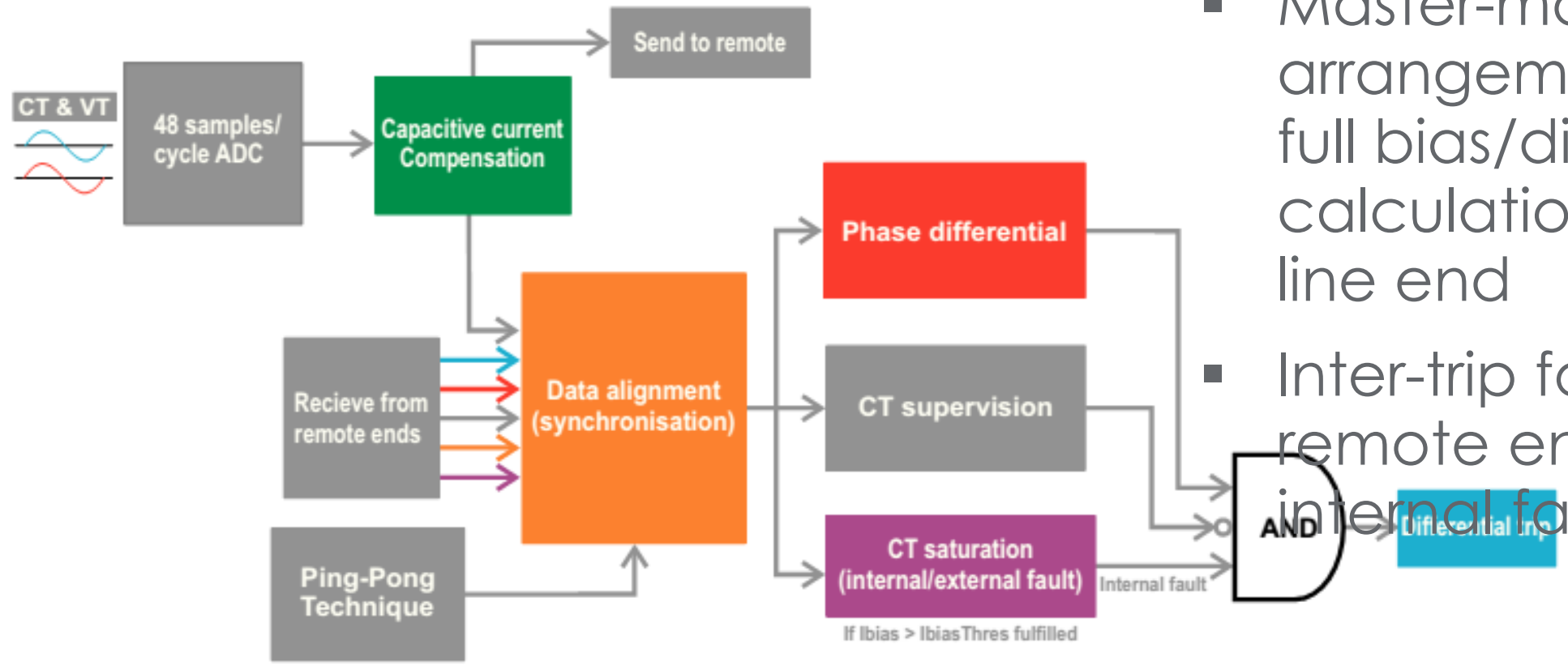
New Multi-ended Differential Protection Highlights



- Innovative **sample-based** algorithm, bias characteristic
- **Sub cycle operating time**, up to 4 ends
- Takes into account **CT saturation**, algorithm reduces CT requirements
- **Capacitive current compensation** with voltage input



New Multi-end Differential Protection Overview



- Master-master arrangement with full bias/diff calculation at each line end
- Inter-trip for all remote ends for internal faults



New Multi-end Differential Protection Phase Differential

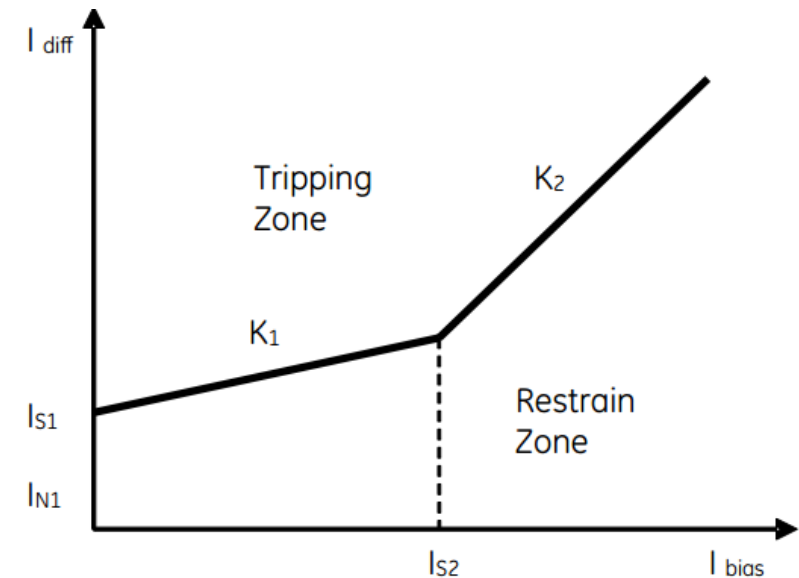
- Bias and differential currents derived from samples, with RMS calculation

$$i_{diff}(n) = \sum_{m=1}^M i_{Tm}(n)$$

$$I_{Tm}(n) = \sqrt{\frac{1}{N} \sum_{k=n-N+1}^n |i_{Tm}(k)|^2}$$

$$I_{diff}(n) = \sqrt{\frac{1}{N} \sum_{k=n-N+1}^n |i_{diff}(k)|^2}$$

$$I_{bias}(n) = \frac{1}{2} \left[\sum_{m=1}^M I_{Tm}(n) \right]$$



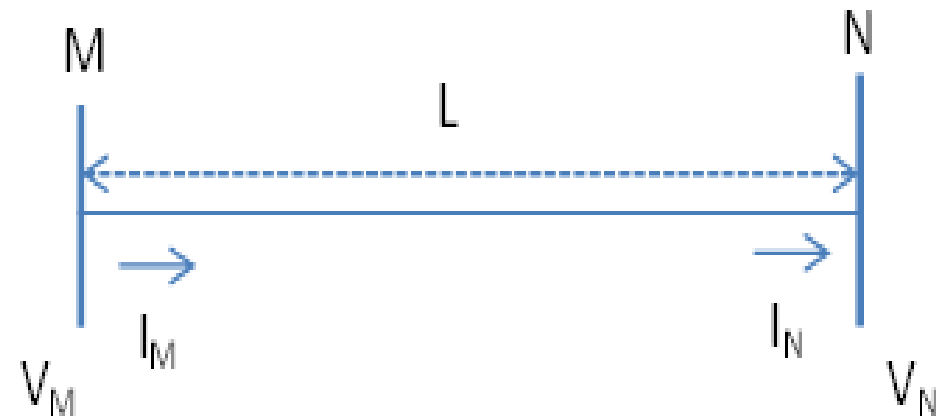
Dual slope bias characteristic



New Multi-end Differential Protection Capacitance compensation (1/3)

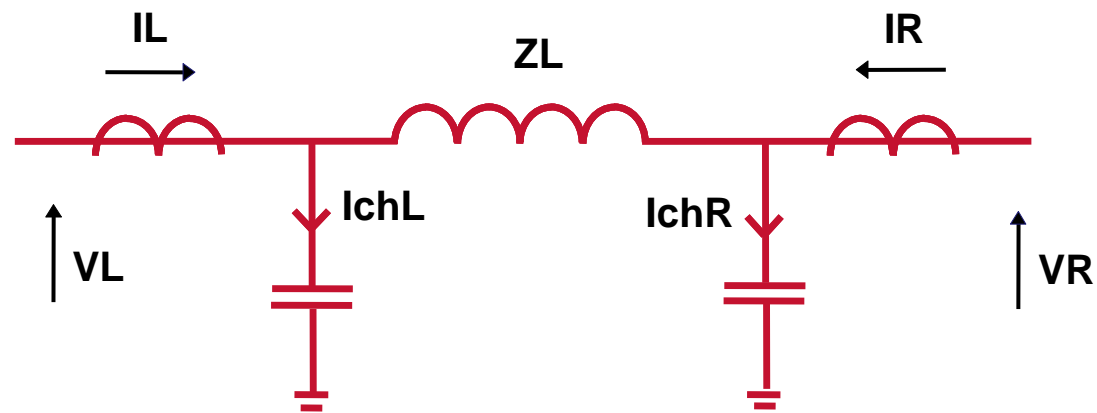
Capacitive current of feeders should be eliminated, especially for overhead lines longer than 50km and cables longer than 10km (typical)

- The objective of capacitive current compensation is to calculate the current at terminal N based on the voltage and current at terminal M
- A distributed parameter line model is used, which is more accurate than the lumped model.

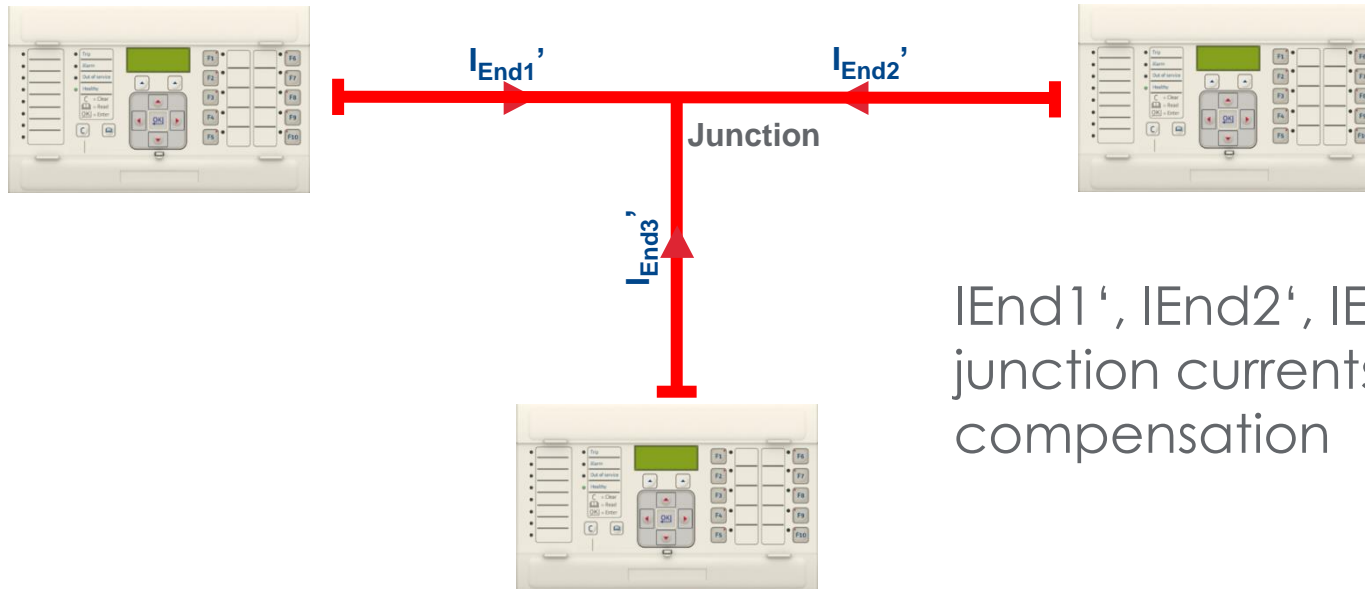


New Multi-end Differential Protection Capacitance compensation (2/3)

- Only the impedance and susceptance per unit length are required
- The function has been transposed from the frequency domain to the time domain so that it can be applied to a sample based technique
- High accuracy especially for topologies with long lines. The calculation error is better than 1%.



New Multi-end Differential Protection Capacitance compensation (3/3)



I_{End1}' , I_{End2}' , I_{End3}' = calculated junction currents after charging current compensation

- Based on local measurement of the current & voltage, each relay can remove capacitive charging current from the line end to the junction and calculate the voltage and current at the junction : I_{End1}' , I_{End2}' , I_{End3}' .
- I_{End1}' , I_{End2}' , I_{End3}' current (with charging component removed) are sent to remote ends for differential calculation.



New Multi-end Differential Protection CT saturation & fault discrimination (1/3)

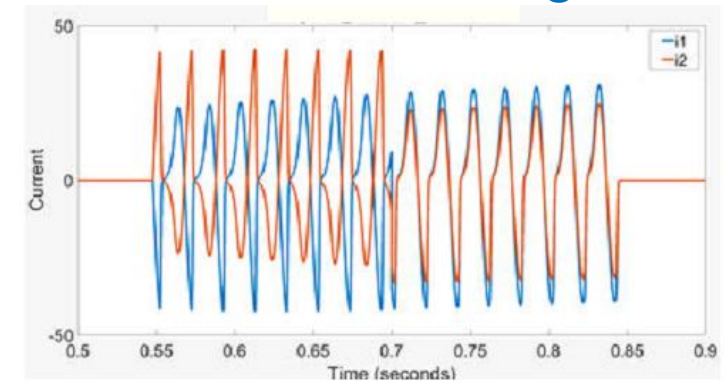
CT saturation detection works using quantities **Ipos** and **Ineg**. **Evolving fault**

$$I_{Pos} = \sum_{k \in Pos} i_k$$

$$I_{Neg} = \sum_{k \in Neg} i_k$$

Sum of positive samples

Sum of negative samples



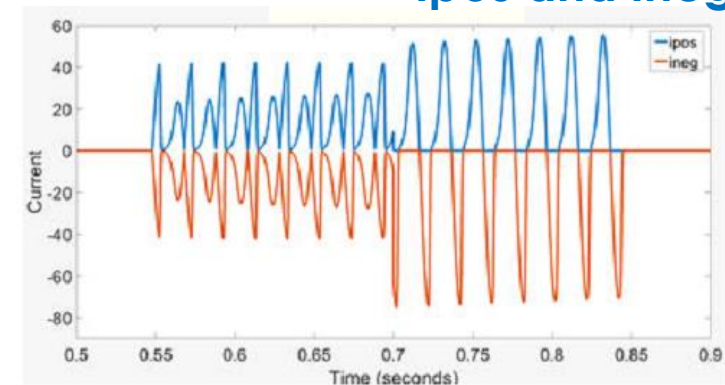
Ipos and Ineg

$$\| I_{Pos}(n) + I_{Neg}(n) \| < \| I_{Pos}(n) - I_{Neg}(n) \|$$

External faults

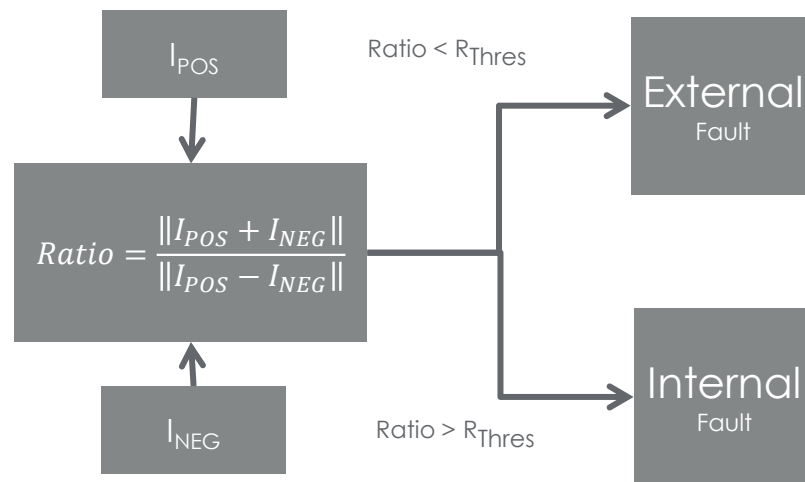
$$\| I_{Pos}(n) + I_{Neg}(n) \| = \| I_{Pos}(n) - I_{Neg}(n) \|$$

Internal faults



New Multi-end Differential Protection CT saturation & fault discrimination (2/3)

Logic for fault discrimination

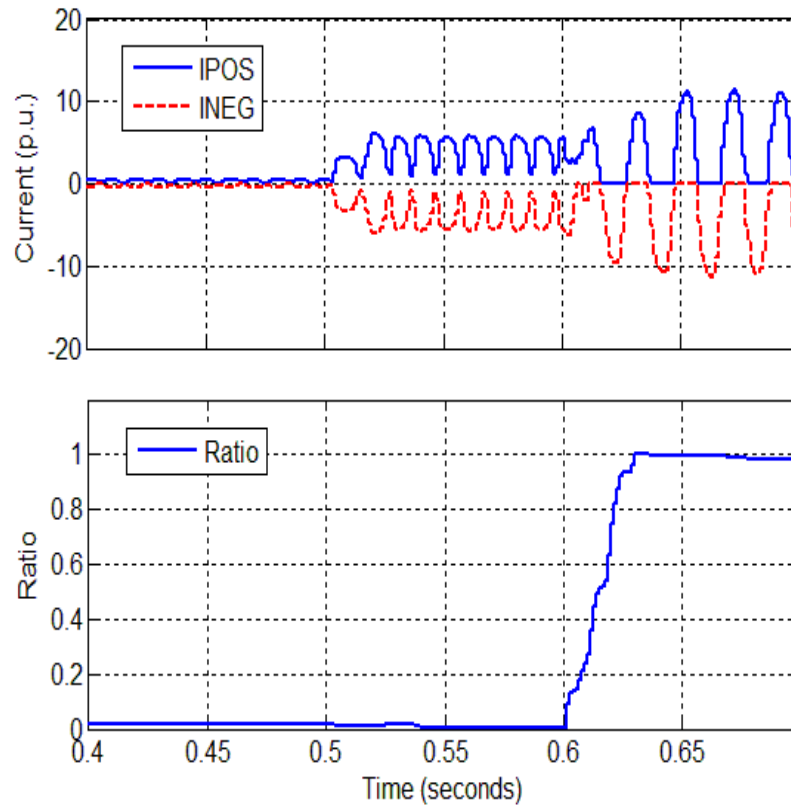


New CT saturation technique reduces CT dimensioning requirements

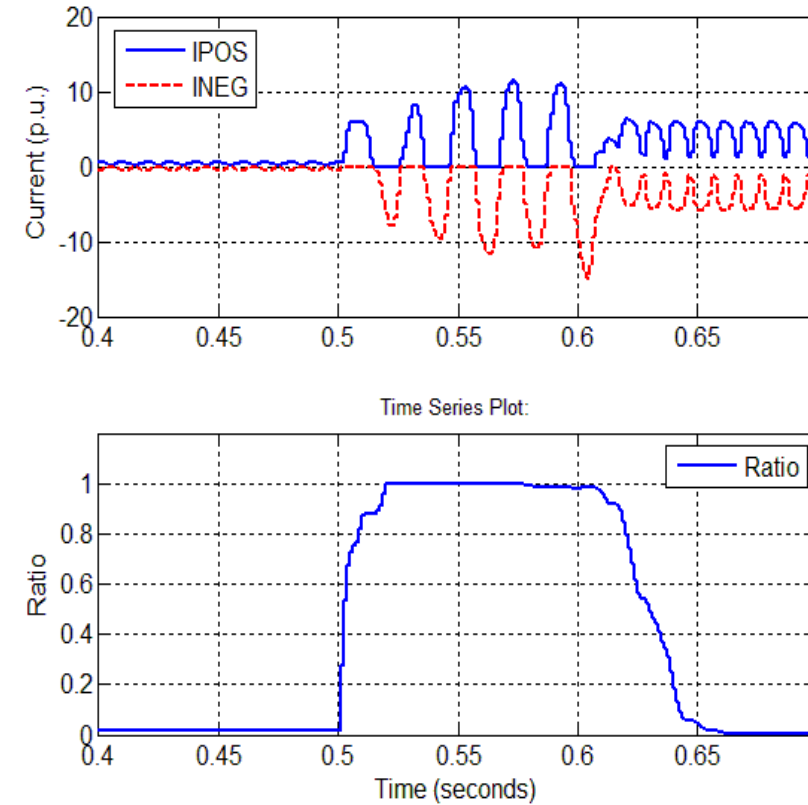


New Multi-end Differential Protection CT saturation & fault discrimination (3/3)

IPOS, INEG and Ratio for external to internal (evolving) fault

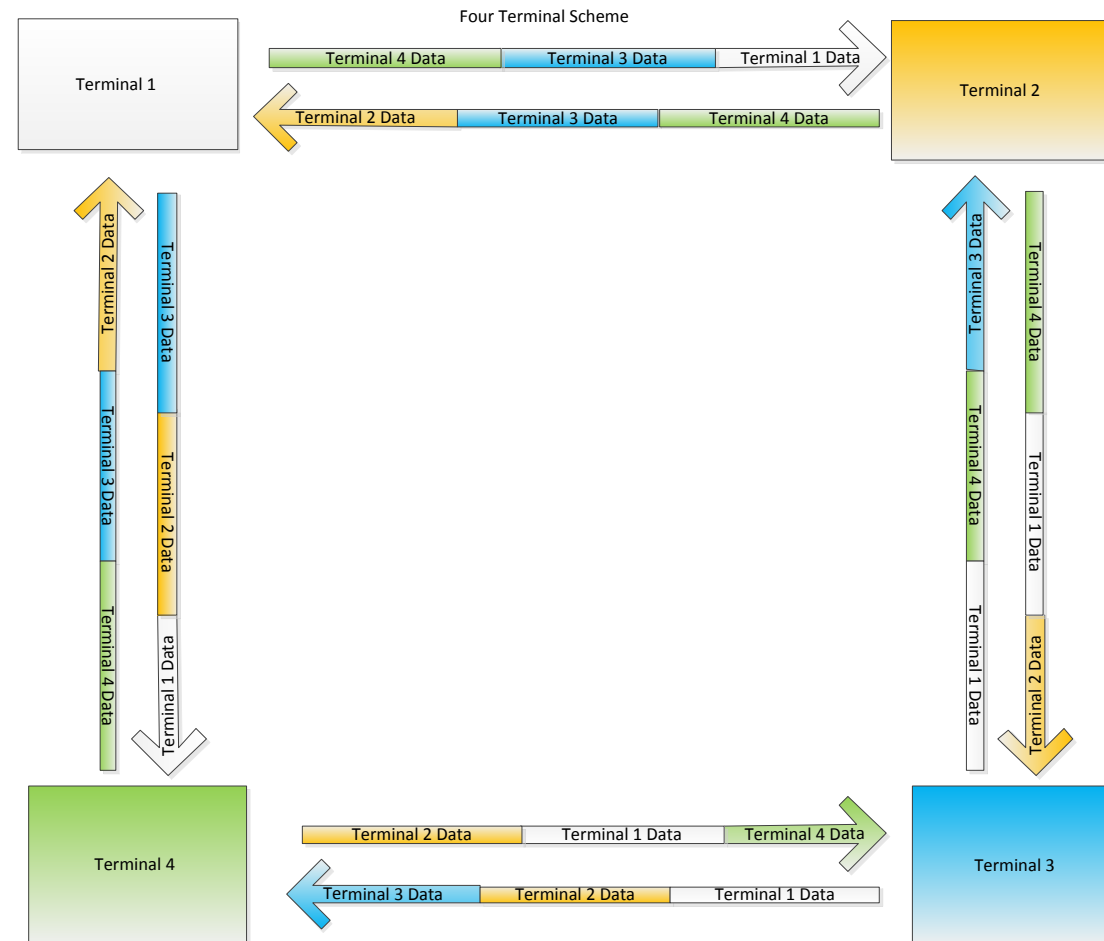


IPOS, INEG and Ratio for internal to external (evolving) fault



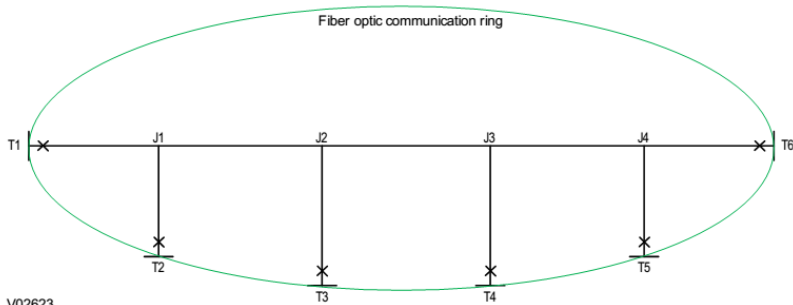
New Multi-end Differential Protection Communication configuration (1/2)

- Ring configuration, with dual channels
- Possibility to mix channel types
- Protocol: IEEE C37.94, 12 x 64kb/s
- Propagation delays upto 64ms acceptable

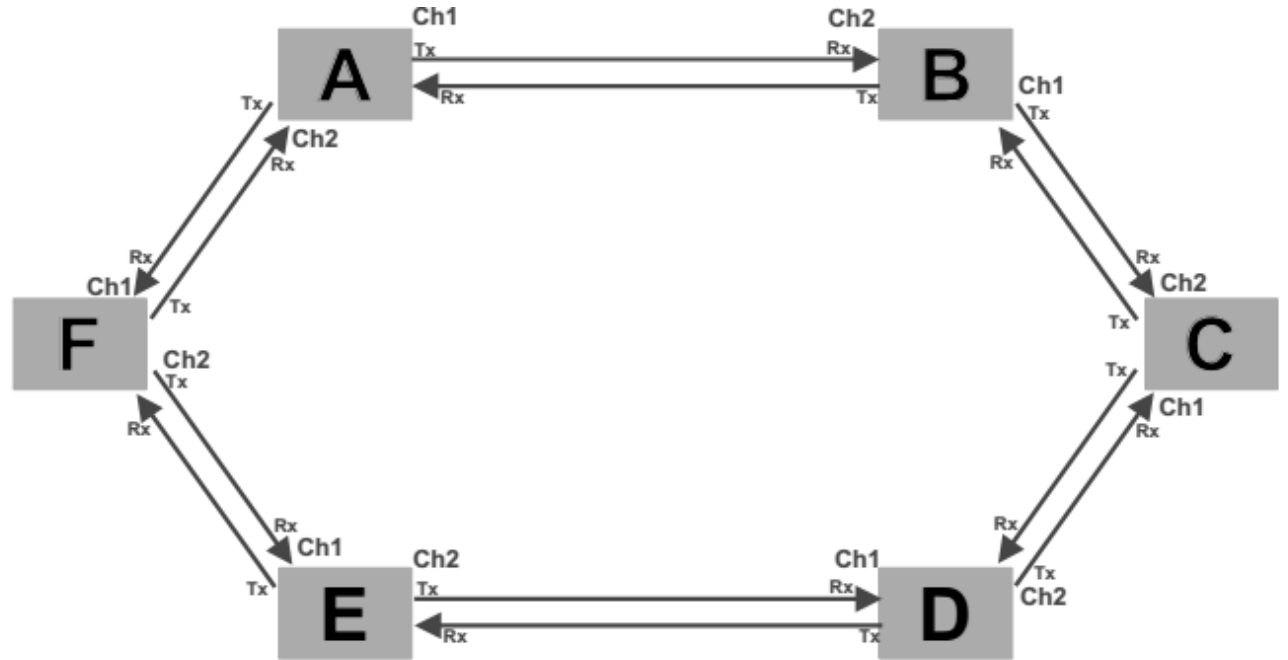


New Multi-end Differential Protection Communication configuration (2/2)

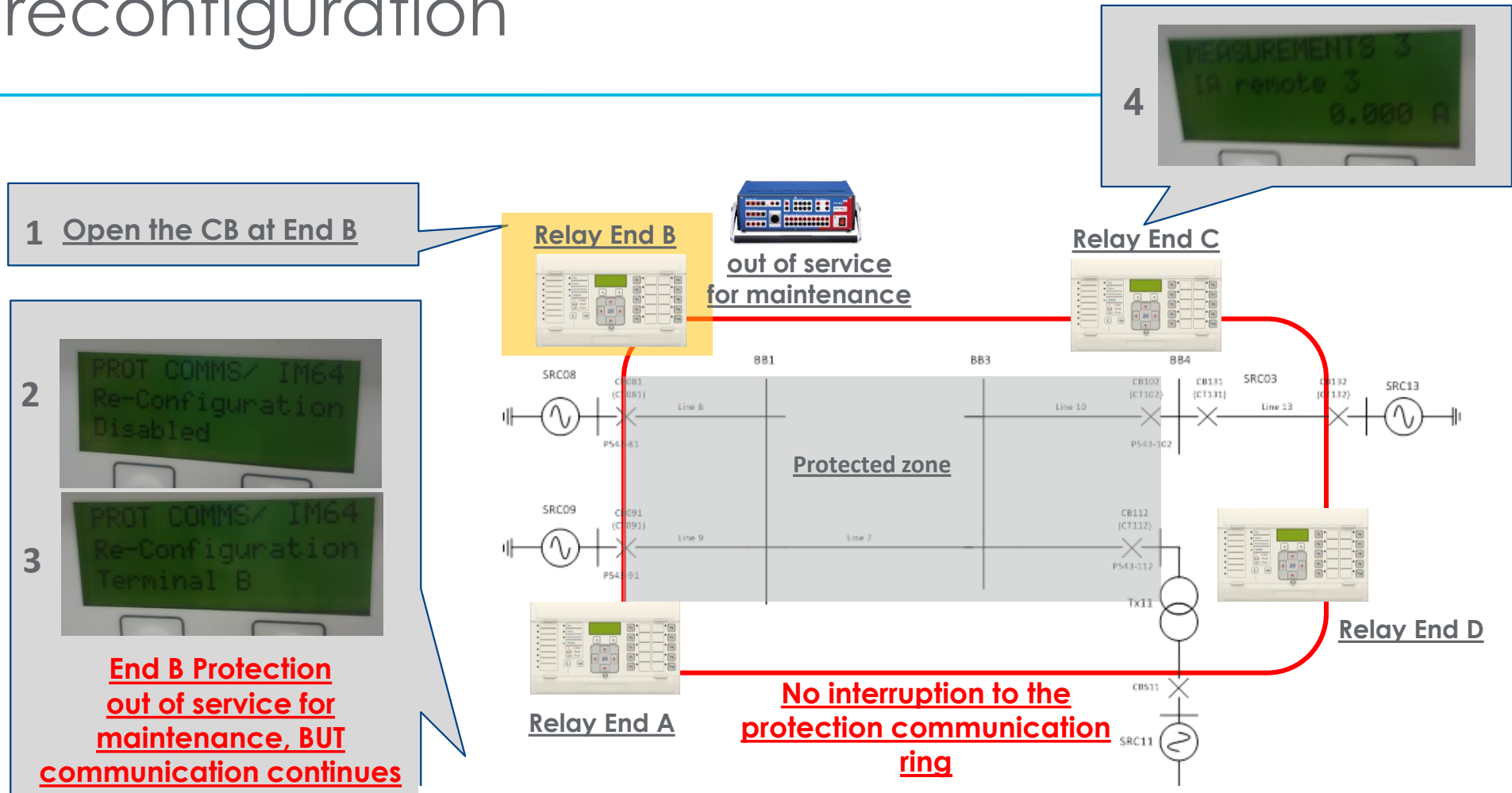
- Upto 6 line ends, thus provision for future expansion
- Ring provides redundancy in case of comms failure



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New Multi-end Differential Protection Scheme reconfiguration



End B Protection out of service for maintenance, BUT communication continues

Any relay
(Reconfiguration command can be sent from any relay,
The relay will get 'reconfiguration confirmation')



